-----Test with the UTE-----

Date: 10/11/2001

*Drivers:* Jose/Juan

*Place:* Carp Park/Campus

*Kind of test, or reason for that this test was done (Ej: To test Slam):* Localisation/Slam, artificial beacons.

*Quantity of test:* 6 in the carp park -2 in the campus

Sensors:

- 1. Name: laser blue *Position:* front, left
- 2. *Name:* Gps gg24. RTK mode-*Position:* Top of the laser
- *3. Name:* INS Watson *Position:* Back part of the ute- From the gps antenna: [3.90;0;-0.30]
- *4. Name:* Compass *Position:* Back of the ute. From the GPS
- 5. Name: Position:
- •••

Files: aaaa1..6, campus1..2, beacons (position the artificial beacons in the car park)

Observations: none